



Basics II: electronic convergence and BZ sampling

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Introduction the SCF-scheme Basic Algorithms used in VASP



Outline

Electronic Convergence

- Introduction
- the SCF-scheme
- Basic Algorithms used in VASP
- 2 Charge Density Mixing
- Sampling the Brillouin Zone
 - Basics
 - BZ Sampling
 - Files and Parameters, Problem Handling



Introduction the SCF-scheme Basic Algorithms used in VASP



Determination of the Electronic Groundstate

Overview

- eigenvalue problem to be solved
- general strategies to solve the KS-equations
- algorithms used in VASP
- choice of the appropriate input parameters
- strategies if concergence fails, error handling



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the Kohn-Sham Groundstate

the Free Energy Functional

• electronic contribution of the Kohn-Sham free energy F_{KS} at finite T:

$$\begin{aligned} F_{KS}[\phi, f, \vec{R}] &= \sum_{n} f_{n} < \phi_{n} |\hat{T}| \phi_{n} > -\sum_{n} \sigma S(f_{n}) \\ &+ E_{H}[\rho] + E_{xc}[\phi, f] + \int V_{ion}(\vec{r}) \rho(\vec{r}) d^{3}\vec{r} \end{aligned}$$

- with contributions of the kinetic energy,
- entropy of non-interacting e⁻,
- Hartree term,
- exchange-correlation energy and the
- ionic potential



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Electronic Convergence

the Free Energy Functional

$$F_{KS}[\phi, f, \vec{R}] = \sum_{n} f_{n} < \phi_{n} |\hat{T}| \phi_{n} > -\sum_{n} \sigma S(f_{n})$$

+ $E_{H}[\rho] + E_{xc}[\phi, f] + \int V_{ion}(\vec{r})\rho(\vec{r})d^{3}\vec{r}$

- \vec{R} : ions' positions,
- f_n: levels' occupancies,
- $\phi: 1 e^-$ orbitals
- electron density $\rho = \sum_{n=1}^{occ} f_n |\psi_n(\vec{r})|^2$
- going beyond DFT,

$$E_{xc}[\phi, f] = \underbrace{E_{xc}^{\text{loc}}[\rho]}_{\text{LDA,GGA}} + \underbrace{E_{x}^{\text{nl}}[\phi, f]}_{\text{XXC}}$$



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the Self-Consisteny Cycle



2 optimization loops

- inner (el): refinement of wavefunctions: optimization of {ψ_n}
- outer (el): refinement of *ρ_{in}* charge density mixing
- outer (ionic) refinement of atoms' positions: minimisation of the forces



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Numerical Determination of the electronic groundstate

Iteration to Self-Consistency

self-consistent solution of $\textbf{H}\Psi=E\Psi$

• old-fashioned:

- **(1)** start with a trial ρ_{in}^{0}
- 2 solve the Schrödinger eqn.
- 3 calculate the new density $\rho_{out} = \sum_{n=1}^{\infty} |\psi_n|^2$
- mix charge densities: $\rho_{new} = n\rho_{in} + (n-1)\rho_{out}$
- **(3)** construct the new Schrödinger eqn. using ρ_{new}
- iterate 2-5 until convergence is reached

slow



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Numerical Determination of the electronic groundstate

Direct Minimization of the Functional

- modern, based on the method of Car-Parrinello:
- $\bullet\,$ used if the diagonalization of H is the bottleneck of the calculation
- minimize the value of the functional $F_n(\vec{r})$

gradient :
$$F_n(\vec{r}) = \left[-\frac{\hbar^2}{2m_e}\nabla^2 + V^{\text{eff}}(\vec{r}, \rho(\vec{r'})) - \epsilon_n\right]\phi_n$$

- start with a set of trial wavefunctions $\phi_n^0(\vec{r})$ with $n = 1, \dots N_e(/2)$ (eg random numbers)
- \bullet converge each band iteratively, starting from $\phi_n^0,$ diagonalizing the Hamiltonian
- supported by VASP (versions up from vasp.4.6)



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Basic Algorithms used in VASP

Overview

- almost all algorithms used by VASP are based on iterative matrix diagonalization schemes
 - blocked Davidson (DAV)
 - 2 conjugate gradient (CG)
 - residual minimization (RMM), direct inversion in the iterative subspace (DIIS)
- a small amount of a residual vector $|R_n >$ is added to the function f to refine f ($f = |\phi_n >, \rho,$)
- in iterative diagonalization methods, $|R(\phi_n) >$ is used to update the wavefunction: $\phi'_n = \phi_n + \lambda R_n$ (in the sense of a steepest descent approach)
- minimize the norm of $|R_n>$



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Basic Algorithms used in VASP

Residual Vectors: wavefunction $(|\phi_n >)$

- start with some trial ϕ_n for an eigenstate n of \hat{H}
- variation of the Rayleigh quotient with respect to $\langle \phi_n | \longrightarrow$ residual vector $|R(\phi_n) >$:

$$\epsilon_n^{\text{appr.}} = \frac{\langle \phi_n | \mathbf{H} | \phi_n \rangle}{\langle \phi_n | \mathbf{S} | \phi_n \rangle} \longrightarrow | \mathcal{R}(\phi_n) \rangle = (\mathbf{H} - \epsilon_n^{\text{appr.}} \mathbf{S}) | \phi_n \rangle$$

 aim: find a matrix K which gives the exact error of the wavefunction (preconditioning), to find the optimal |R_n >



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Preconditioning (I)

- aim: find a unitary matrix ("rotation matrix") K that yields:
- the exact error in the trial wavefunction (ideally in a single step)
- a preconditioned residual vector $|p_n
 angle={\bf K}|R_n
 angle$
- based on the ansatz of Teter *et.al*: as *E_{kin}* dominates **H** for large *G*, → **K** = **K**(³/₂*E_{kin}*(*R*)) G. Kresse, J. Furthmüller, Phys. Rev. **B 54**, 11169, (1996),

$$\begin{aligned} \mathbf{G}|\mathbf{K}|\mathbf{G}'\rangle &= \delta_{\mathbf{G}\mathbf{G}'} \frac{27+18x+12x^2+8x^3}{27+18x+12x^2+8x^3+16x^4}, & \text{with} \\ x &= \frac{\hbar^2}{2m} \frac{G^2}{\frac{3}{2}E^{\mathrm{kin}}(\vec{R})} \end{aligned}$$



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Basic Algorithms used in VASP

Preconditioning (II)

 preconditioning using hybrid functionals (M. Marsman, G. Kresse, to be published): the optimal K to optimize

$$\begin{split} \bar{\mathbf{F}}[\mathbf{K},f'] &= \sum_{n} \sum_{kl} f'_{n} \mathbf{K}^{*}_{nl} \mathbf{K}_{nk} < \phi_{l} | \hat{\mathcal{T}} | \phi_{k} > -\sum_{n} \sigma S(f'_{n}) \\ &+ E_{H}[\rho] + \bar{E}_{xc}[\mathbf{K},f'] + \int V_{\mathrm{ion}(\vec{r})} \rho(\vec{r}) d^{3}\vec{r} \end{split}$$

with $\rho(\vec{r}) = \sum_{n} \sum_{kl} f'_{n} \mathbf{K}^{*}_{nl} \mathbf{K}_{nk} \phi^{*}_{l}(\vec{r}) \phi_{k}(\vec{r})$

- $\phi'_n = \sum_m \mathbf{K}_{nm} \phi_m$
- linearization of E_{XC} around the present set of orbitals:
- matrix elements for a fixed, non-local Fock V_{xc} calculated at the start of the self-consisteny procedure, not updated during the search of the optimal K_{nm} .



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Basic Algorithms used in VASP

Blocked Davidson Scheme (DAV)

- **(**) select subset $\{\phi_k^1 | k = 1, ..., n_1\}$ of all bands $\{\phi_n | n = 1, ..., N_{\text{bands}}\}$
- Optimize \u03c6_k by adding the orthogonalized preconditioned |R_n > (|\u03c6_n >) to the presently considered subspace
- 3 Rayleigh Ritz optimization in the space spanned by these vectors ("sub-space" rotation in the 2 * n1 dim. space)
- determine n_1 lowest vectors $\{\phi_k^2 | k = 1, ..., n_1\}$
- iterate 2-4 if required
- **6** store the optimized w.f. back in the set $\{\phi_k | k = 1, ..n_1, .., N_{\text{bands}}\}$.
- **(2)** continue steps 1-4 with next sub-block $\{\phi_k^1 | k = n_1 + 1, ..., 2n_1\}$
- 3 after each block of band has been optimized: Rayleigh Ritz optimization in the space $\{\phi_k | k = 1, ..., N_{\text{bands}}\}$
- **2** approximately a factor of 1.5-2 slower than RMM-DIIS, but always stable.



Basic Algorithms used in VASP



Basic Algorithms used in VASP

Blocked Davidson (DAV)

optimize this subset 2

$$\phi_{k}^{1} / g_{k}^{1} = \underbrace{\left(1 - \sum_{n=1}^{N_{\text{bands}}} |\phi_{n}\rangle\langle\phi_{n}|\mathbf{S}\right)}_{\text{orthonormalization, operator}} \mathsf{K}\left(\mathsf{H} - \epsilon_{\text{app}}\mathsf{S}\right)\phi_{k}^{1} | k = 1, ..., n_{1} >$$

orthonormalization operator

3 Rayleigh Ritz optimization $\longrightarrow \{\phi_k^2 | k = 1, n_1\}$

add additional preconditioned residuals

$$\phi_k^2 / g_k^1 / g_k^2 = (1 - \sum_{n=1}^{N_{\text{bands}}} |\phi_n > < \phi_n | \mathbf{S}) \mathbf{K} (\mathbf{H} - \epsilon_{\text{app}} \mathbf{S}) \phi_k^2 >, | k = 1, .., n_1$$

add a fourth set of preconditioned vectors if required,...



Introduction the SCF-scheme Basic Algorithms used in VASP



Basic Algorithms used in VASP

Conjugate Gradient (CG)

- strictly sequential: bands are optimized one after another
- optimization of F_{KS} with respect to the wavefunctions yields a gradient $|g_n >$

$$|g_n\rangle = f_n \left(1 - \sum_m |\phi_m\rangle < \phi_m|\right) \hat{H} |\phi_n\rangle + \underbrace{\sum_m \frac{1}{2} \mathsf{H}_{nm}(f_n - f_m) |\phi_m\rangle}_{2}$$

with $\hat{H} = \hat{T} + \hat{V}_{ ext{ion}} + \hat{V}_{H}(
ho) + \hat{V}_{ extsf{xc}}[\phi, f]$

- \hat{V}_{xc} includes the local V_{xc} (and the non-local screened Fock-exchange).
- 1: changes in F_{KS} with respect of changes in the φ orthogonal to the subspace spanned by the current φ
- 2: changes in F_{KS} with the subspace spanned by the current φ (=0 if only occupied orbitals are included)



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Basic Algorithms used in VASP

Conjugate Gradient (CG)

• search direction determined by using Loewdin's perturbation theory:

$$\mathbf{U}_{nm} = \delta_{nm} - \Delta s \frac{\mathbf{H}_{nm}}{\mathbf{H}_{mm} - \mathbf{H}_{nn}}, \quad \phi'_n = \sum_m \mathbf{U}_{nm} \phi_m$$

U. . . unitary matrix, chosen such that $<\phi_n'|\mathbf{H}|\phi_m'>=\epsilon_m\delta_{nm}$

- step direction $\approx \mathbf{H}_{mm} \mathbf{H}_{nn}$
- Δs step width along the search direction
- implemented algorithms include:
 - (preconditioned) steepest descent
 - (preconditioned) conjugated gradient



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Basic Algorithms used in VASP

Residual Minimization - direct inversion in the iterative subspace (RMM-DIIS)

- most time consuming step in CG: orthonormalization of the preconditioned residual vector to the current set of trial wavefunctions (for each single band update)
- avoided by minimizing the norm of the residual vector instead of the Rayleigh Ritz quotient
 P. Pulay, Chem. Phys. Lett.**73**,393 (1980), D.M. Wood, A. Zunger, J. Phys A, 1343 (1985)).
- each vector is optimized individually
- fast
- drawback: always finds the vector which is closest to the initial trial vector: → if the initial set does not span the real ground state, some states may be "missing" in the final solution.



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Residual Minimization - direct inversion in the iterative subspace (RMM-DIIS)

- () calculate a preconditioned residual vector $\mathbf{K}|R_m^0>=\mathbf{K}|R(\phi_m^0)>$
- $\textcircled{0} \longrightarrow {\sf new residual vector } |R^1_m>=|R(\phi^1_m)>$

• search for the linear combination of $|\phi_m^0 > \text{and } |\phi_m^1 >$, $|\phi_m^M > = \sum_{i=0}^M \alpha_i |\phi_m^i >$ (here: M = 1), yielding $|R_m^M > = \sum_{i=0}^M \alpha_i |R_m^i >$ minimize ||R|| by determining the lowest eigenvector/eigenvalue of $\sum_{j=0}^M < R_m^i |R_m^j > \alpha_j = \epsilon \sum_{j=0}^M < \phi_m^i |\mathbf{S}| \phi_m^j > \alpha_j$

() start from 1, using $|\phi_m^M >$ and $|R_m^M >$



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Basic Algorithms used in VASP

Further Algorithms

- based on CG: simultaneous update of all orbitals
- MD-like Damped velocity friction algorithm (see lecture 3) (requires the definition of a timestep)
- exact diagonalization: whenever there is a substantial amount (> 30-50%) of unoccupied bands (eg for GW calculations)
- subspace rotation and diagonalization in the sub-space spanned by NBANDS



Introduction the SCF-scheme Basic Algorithms used in VASP



Parameters to be set in INCAR

choice of the electronic convergence algorithms

- ALGO algorithms to be used (alternative: IALGO): implemented in vasp.4.6 and vasp.5
 Normal (DAV) | Fast (DAV+RMM-DIIS) | VeryFast (RMM-DIIS) |
 - implemented in vasp.5 only
 - Damped (damped MD) | All (damped MD+precond. CG) Exact | Diag | Subrot | Eigenval | None | Nothing |
- for Hybrid functionals, always use direct optimization (A, Exact)
- LDIAG (True | False): perform subspace diagonalization
- TIME time step for damped MD-based algorithms





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1 Electronic Convergence

- Introduction
- the SCF-scheme
- Basic Algorithms used in VASP

2 Charge Density Mixing

- 3 Sampling the Brillouin Zone
 - Basics
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 - Files and Parameters, Problem Handling





DIIS Mixing Algorithms

- calculation of the input density for the next el. step from $\rho_{new} = m\rho_{in} + (m-1)\rho_{out}$:
- minimize the norm of the residual vector $R[\rho_{in}] = \rho_{out}[\rho_{in}] \rho_{in}$
- assume R can be linearized around $\rho_{\rm sc}$:

$$\begin{aligned} R[\rho] &= -\mathbf{J}(\rho - \rho_{\rm sc}) \\ R[\rho] &\approx R[\rho]^{(m)} - \mathbf{J}^{(m)}(\rho^{(m)} - \rho_{\rm sc}) \\ \rho^{(m+1)} &= \rho^{(m)} + \mathbf{G}^{(m)}(\rho^{(m)}_{out} - \rho^{(m)}_{in}) \\ \mathbf{G}^{(m)} &= -\mathbf{J}^{(m)-1} \end{aligned}$$





DIIS Mixing

- $\mathbf{J} = 1 \chi \mathbf{U}$: "charge dielectric" (Jacobian) matrix:
- in a system with a dielectric susceptibility χ , an external charge perturbation $(\Delta \rho)$ leads to a change in the potential $\mathbf{U} = \frac{4\pi e^2}{\mathbf{q}^2}$.
- model dielectric function implemented in VASP: G.P. Kerker, Phys.Rev.B**23**, 3082 (1981):

$$\mathbf{J} ~pprox$$
 AMIX $\cdot \max(rac{q^2}{q^2+ ext{BMIX}}, ext{AMIN})$

 $\texttt{BMIX} \ \ldots \ \boldsymbol{q} - \mathrm{cutoff}$ wavevector for the Kerker approx.





DIIS Mixing

- the convergence behaviour is determined by the width of the eigenvalue spectrum of ${\bf J}=1-\chi\frac{4\pi e^2}{{\bf g}^2}$
- insulators, semiconductors: constant, indepedent of the system size L ⇒ good convergence
- metals:
 - $\bullet\,$ short wavelength limit (large $q)\longrightarrow J\approx 1:$ no screening
 - long wavelength limit: the screening term dominates J: \longrightarrow J \approx q⁻² \sim L²

 \Rightarrow the width of the spectrum is proportional to the square of the longest dimension of the lattice

 \Rightarrow poor convergence, possibly charge sloshing.





Available Mixing Algorithms

- Linear Mixing (n = AMIX) $\rho_{in}^{(m+1)} = n\rho_{in}^{(m)} + (n-1)\rho_{out}^{(m)}$
- Kerker Mixing (BMIX)

$$\rho_{mix}(G) = \rho_{in}(G) + \texttt{AMIX} \cdot \max(\frac{G^2}{G^2 + \texttt{BMIX}}, \texttt{AMIN})[\rho_{out}(G) - \rho_{in}(G)]$$

- Broyden Mixing, (WC = 0)
 D.D.Johnson, Phys.Rev.B38, 12807 (1988)
 information of the current iteration (m) updates J⁻¹ but also overrides information of from previous iterations
- Pulay Mixing (WC > 0)
 P.Pulay, Chem. Phys. Lett 73, 393 (1980)
 information from all previous iterations is included with equal weights.





Available Mixing Algorithms

• Tchebycheff mixing via a 2nd order equation of motion, using a simple velocity Verlet algorithm H.Akai and P.H.Dederichs, J.Phys.C **18**, 2455 (1985)

$$\ddot{\rho}_{mix}(G) = 2 \cdot \mathbf{J}(\mathbf{G})[\rho_{out}(G) - \rho_{in}(G)] - \mu \dot{\rho}_{in}(G)$$
$$\mu = \text{friction (damping) factor}$$





Parameters to be set in INCAR

- IMIX: Mixing type:
 - 0 (no mixing) | 1 (Kerker) | 2 (Tchebycheff) |
 - 4 Broyden (WC=0) or Pulay (WC>0)
- Kerker mixing BMIX, BMIX_MAG: cutoff wavevectors
- for Boyden-type mixing: INIMIX, MIXPE, MAXMIX, WC
 - INIMIX functional form of the initial mixing matrix
 - MIXPRE metric for the Broyden scheme
 - MAXMIX max. # of steps stored in the Broyden scheme
 - WC weight factor for each iteration





what to do if convergence fails (DFT-level)





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Some Basics

Periodicity

- perfect periodic lattices: translational symmetry: each unit cell is repeated at *R* by shifting it by N ⋅ *ā* (*ā* = n₁*ā*₁ + n₂*ā*₂ + n₃*ā*₃ lattice vector)
 with respect to some "origin of the lattice":
- applying a translation operator $\hat{T}_{\vec{a_i}}$: $\hat{T}_{\vec{a_i}}(\vec{0}) = \vec{R}$
- \hat{T} and \hat{H} commute ($[\hat{T}, \hat{H}] = 0$) $\Rightarrow \hat{T}$ and \hat{H} have the same eigenfunctions.

$$\begin{array}{llll} \hat{T}_{\vec{R}} \mid \! \vec{0} & = & \mid \! \vec{R} \\ \left\langle \vec{R} \mid \! \vec{R} \right\rangle & = & \lambda^* \lambda \cdot \left\langle \vec{0} \mid \! \vec{0} \right\rangle \\ \Rightarrow \lambda^* \lambda & = & 1 \\ \Rightarrow \lambda & = & e^{i\vec{k}}, \quad k \in \mathbf{R} \end{array}$$



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Some Basics (continued)

periodicity (continued)

• translation by a lattice vector \vec{R}

$$\left. \hat{T}_{\vec{R}} \left| \vec{0} \right\rangle = \left| \vec{R} \right\rangle = e^{i \cdot \vec{k} \cdot \vec{R}} \cdot \left| \vec{0} \right\rangle$$

• \Rightarrow for any Ψ that satisfies the Schrödinger equation in a periodic potential, $\exists \vec{k}$ such, that a translation by \vec{R} is equivalent to a multiplication by the phase factor $e^{i \cdot \vec{k} \cdot \vec{R}}$, eg. for e^{-} -waves

$$\Psi(\vec{r}+\vec{R})=e^{i\cdot\vec{k}\cdot\vec{R}}\Psi(\vec{r}).$$



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periodicity: Range of \vec{k}

for any lattice vector of the reciprocal lattice defined by unit vectors (*b_i* = 2π/Ω *a_j* × *a_k*) *G_n* = m₁*b*₁ + m₂*b*₂ + m₃*b*₃,
let *k'* = *k* + *G_n*,

$$\Psi_{\vec{k'}}(\vec{r}+\vec{R})=e^{i\cdot\vec{k'}\cdot\vec{R}}\Psi(\vec{r})=e^{i\cdot\vec{k}\cdot\vec{R}}\underbrace{e^{i\cdot\vec{G_n}\cdot\vec{R}}}_{\equiv 1}\Psi(\vec{r})$$

range of allowed values for k
 : within the first Brillouin zone (BZ)

$$0 < k \le \frac{2\pi}{a} \text{ or } -\frac{\pi}{a} < k \le \frac{\pi}{a}$$

• for finite crystals:
$$\# \vec{k} \neq \infty$$

 \rightarrow ? allowed number of $\vec{k} \rightarrow$ quantization of \vec{k}



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Some Basics (continued)

Quantisation of \vec{k}

- cyclic Born-von Kármán boundary conditions $(I = N_1 a_1)$
- unperturbed (ideal) crystal (eg 1D chain with length /),
- N_1 : number of unit cells of the macroscopic crystal along x
- N₁: large enough to provide that effects of the crystal shape are negligible.

$$\begin{split} \Psi(\vec{x} + N_1 \vec{a}_1) &= \Psi(\vec{x}), & \vec{\nabla} \Psi(\vec{x} + N_1 \vec{a}_1) = \vec{\nabla} \Psi(\vec{x} \\ \Psi(x + N_1 a_1) &= e^{ik_1 N_1 a_1} \Psi(x) & \Rightarrow e^{ik_1 N_1 a_1} = 1 \\ k_1 N_1 a_1 &= 2\pi m_1 & \Rightarrow k_1 = \frac{2\pi m_1}{N_1 a_1}, & m_1 \in Z \\ 0 &< m_1 \leq N_1 & \text{or} & -\frac{N_1}{2} < m_1 \leq \frac{N_1}{2} \end{split}$$



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Some Basics (continued)

energy bands

• proper wavefunctions in a periodic lattice: $\Psi_{\vec{k}}(\vec{r}) = \underbrace{e^{i\vec{k}\vec{r}}}_{\text{BlochFactor}} \cdot u(\vec{r})$

where $u(\vec{r})$ is a cell-periodic function of the lattice

• the eigenvalues $\epsilon_n(\vec{k})$ of a crystal of *fixed*, *finite* volume V: *discrete* spectrum of \hat{H} :

$$\hat{H}\Psi_{\vec{k}+\vec{G_n}}(\vec{r})=\hat{H}\Psi_{n\vec{k}}(\vec{r})=\epsilon_{\vec{k}+\vec{G_n}}\Psi_{n\vec{k}}(\vec{r}),\quad\epsilon_{\vec{k}+\vec{G_n}}=\epsilon_n(\vec{k})$$

- $\forall n$: the set of electronic levels $\epsilon_n(\vec{k})$ is the " n^{th} energy band".
- the eigenstates and -values are periodic with k in the reciprocal lattice ("extended zone sheme")



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Some Basics (continued)



Supercells

- example: bandstructure of (super)cells containing 1 (2) atoms with 2 s-electrons
- $\vec{a}' = 2\vec{a} \Rightarrow \vec{k}_1' = \frac{1}{2}\vec{k}_1$
- folding of the bandstructure

cell size	1 <i>a</i>	2 <i>a</i>
# bands	1	2
\vec{k} -pts	Г	Г
	Δ	Х
	Х	Г

• \Rightarrow for constant \vec{k} -grid-density: $N(\vec{k'}) = \frac{1}{2}N(\vec{k})$



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Sampling of the Brillouin Zone

Integrals over the Brillouin zone I_{BZ} :

- for the calculation of e.g. Density of states (DOS), Charge densities,
- Integrals over the Brillouin zone are usually replaced by sums over special k-points:

$$I(\epsilon) = \frac{1}{\Omega_{\rm BZ}} \int_{\rm BZ} F(\epsilon) \delta(\epsilon_{n\vec{k}} - \epsilon) d\vec{k} \longrightarrow \sum_{\vec{k}} w_{\vec{k}i} F(\epsilon) \delta(\epsilon_{n\vec{k}} - \epsilon)$$

• Symmetry of the lattice: $BZ \longrightarrow irreducible BZ$ (IBZ)

$$\Omega_{\mathrm{IBZ}} = rac{\Omega_{\mathrm{BZ}}}{N_{\hat{R}}}$$

• $N_{\hat{R}}$: number of symmetry operations of the point group



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Sampling of the Brillouin Zone

\vec{k} -mesh generation

the BZ should be covered by equally-spaced k-point grids,
 e.g. Monkhorst-Pack meshes
 H.J. Monkhorst, J.D. Pack, PRB 13, 5188, (1976)

$$\vec{k} = \vec{b}_1 \frac{n_1 + s_1}{N_1} + \vec{b}_2 \frac{n_2 + s_2}{N_2} + \vec{b}_3 \frac{n_3 + s_3}{N_3}$$

- \vec{b} unit vector of the BZ
- s_i optional shift along direction i
- N_i number of subdivisions along i



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example of a MP-mesh of a 2D square lattice



Mesh data

- full BZ: $N_1 = N_2 = 4 \Rightarrow$ $n_{\vec{k}}(BZ) = 16$
- $N_{\hat{R}} = 4 \Rightarrow n_{\vec{k}}(IBZ) = 4$
- $w_{\vec{k}_1} = w_{\vec{k}_2}(\mathsf{IBZ}) = \frac{4}{16} = \frac{1}{4}$
- $w_{\vec{k}_3} = \frac{8}{16} = \frac{1}{2}$
- $\frac{1}{\Omega_{\text{BZ}}} \int_{BZ} F(\vec{k}) d\vec{k} \longrightarrow$ $\frac{1}{4}F(\vec{k}_1) + \frac{1}{4}F(\vec{k}_2) + \frac{1}{2}F(\vec{k}_3)$



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example: bandstructure energy



e.g: one s-like band

• $F(\vec{k}) = \epsilon(\vec{k})$

•
$$E = \sum_{k} w_{k_i} \epsilon_{k_i}$$

- Γ : no nodes in $\Psi \Rightarrow \epsilon = \min$
- X: max # of nodes in $\Psi \Rightarrow \epsilon = \max$
- to increase the accuracy:
- increase the density of the \vec{k} -mesh



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Smearing Methods

problem in metallic systems: some bands cross the Fermi level $E_F = \mu$

 \Rightarrow discontinuity of the occupancy \emph{f} of bands at $\emph{E_F}=\mu$



band n crossing E_f

• eg: bandstructure energy

$$E_b = \sum_{n,\vec{k_i}} w_{\vec{k_i}} \epsilon(\vec{k_i}, n) f(\epsilon(\vec{k_i}, n) - \mu)$$

• ocupancy of state $(\vec{k_i}, n)$

$$f(\epsilon(\vec{k_i}, n) - \mu) = \{ \begin{array}{ccc} 1 & \ldots & \epsilon(\vec{k_i}, n) \leq \mu \\ 0 & \ldots & \epsilon(\vec{k_i}, n) > \mu \end{array} \}$$



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Smearing Methods

Fermi-Dirac smearing

$$f\left(\frac{\epsilon_{(n,\vec{k})}-\mu}{\sigma}\right) = \frac{1}{\exp\left(\frac{\epsilon_{(n,\vec{k})}-\mu}{\sigma}\right) + 1}$$

- $\sigma = k_B T$... smearing parameter (\approx electronic T of the system)
- energy *E* is no longer variational with respect to the partial occupacies *f*
- the new variational functional is the Free energy F $F = E - \sum_{n} \sigma S(f_n)$
- S: entropy of a system of non-interacting electrons at a finite temperature T

•
$$S(f) = -[f \ln f + (1-f) \ln(1-f)]$$



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Smearing Methods

Gaussian Smearing

- levels are broadened with a Gaussian function
- f is the integral of the Gaussian function:

•
$$f\left(\frac{\epsilon_{n,\vec{k}}-\mu}{\sigma}\right) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp^{\left(\frac{\epsilon_{n,\vec{k}}-\mu}{\sigma}\right)^2}, \quad \int f = \frac{1}{2} \left[1 - \operatorname{erf}\left(\frac{\epsilon_{n,\vec{k}}-\mu}{\sigma}\right)\right]$$

- \bullet analytical inversion of the error-function erf does not exist
- \Rightarrow S and F cannot be written in terms of f,

•
$$S\left(\frac{\epsilon-\mu}{\sigma}\right) = \frac{1}{2\sqrt{\pi}}\exp^{-\left(\frac{\epsilon-\mu}{\sigma}\right)}$$

- $\bullet~\sigma$ has no physical interpretation.
- variational functional $F(\sigma)$ differs from E(0).
- Forces: $\vec{F}(F(\sigma))$ are not necessarily equal to $\vec{F}(E(0))$.
- workaround: extrapolation to $\sigma \longrightarrow 0$:



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Smearing Methods

Methfessel-Paxton smearing



- generalization of Gaussian broadening with functions of higher order
- expansion of stepfunction in a complete set of orthogonal functions:
- Hermite polynomials of order N
- term of *N* = 0: integral over Gaussians



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Smearing Methods

Methfessel-Paxton smearing



MP smearing

- Hermite-polynomial of order N $f_0(x) = \frac{1}{2} (1 - erf(x))$ $f_N(x) =$ $f_0(x) + \sum_{m=1}^{N} A_m H_{2m-1}(x) e^{-x^2}$ $S_N(x) = \frac{1}{2} A_N H_{2N}(x) e^{-x^2}$
- deviation of F(σ) from E(0) only of order 2+N in σ
- extrapolation for σ → 0 usually not necessary, but possible:
- $E(0) \approx \hat{E}(\sigma) = \frac{1}{N+2} ((N+1)F(\sigma) + E(\sigma))$



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Smearing Methods

Methfessel-Paxton Smearing

- MP of order N leads to a negligible error, if F(ε) is representable as a polynomial of degree 2N around ε_F.
- linewidth σ can be increased for higher order N to obtain the same accuracy
- "entropy term": S = σ Σ_n S_N(f_n) describes deviation of F(σ) from E(σ).
 ⇒ if S < few meV: Ê(σ) ≈ F(σ) ≈ E(σ) ≈ E(0).

 \Rightarrow forces correct within that limit.

• in practice: smearings of order N=1 or 2 are sufficient



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Tetrahedron Intrgration





The Linear Tetrahedron Method

- (I)BZ is subdivided into tetrahedra spanned by the *k*-points
- function X to be integrated: linearly interpolated between the tetrahedra $\longrightarrow \bar{X}$
- tetrahedra are remapped onto the \vec{k} -points, \vec{k} -points have effective weights (\approx occupancies)

$$\mathbf{w}_{nj} = rac{1}{\Omega_{\mathrm{BZ}}} \int\limits_{\Omega_{\mathrm{BZ}}} d\vec{k} c_j(\vec{k}) f\left(\epsilon_n(\vec{k})\right)$$

•
$$\bar{X} = \sum_{j=1}^{4} c_j(\vec{k}) X(\vec{k_j}) \quad \longleftarrow \int \bar{X}$$



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Tetrahedron Intrgration



Possible Drawbacks of the Linear T.M.

- $\geq 4\vec{k}$ -pts necessary, Γ must be included
- tetrahedra can break the symmetry of the Bravais lattice
- linear interpolation of *f* may under- or overestimate the real curve
- the errors due to this linear interpolation only cancel for full bands (problem for metals)
- the afforded density of the \vec{k} -mesh (# of tetrahedra) can be large



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T.M., Blöchl Corrections

improvements, drawbacks

P.Blöchl et.al., PRB49, 16223 (1994)

• for metals: correction of quadratic errors is possible

$$\delta w_{\vec{k}n} = \sum_{\mathrm{T}} \frac{1}{40} D_{\mathrm{T}}(E_F) \sum_{j=1}^{4} (\epsilon_{jn} - \epsilon_{\vec{k}n})$$

 $(T \dots \text{ tetrahedra, } D \dots \text{ DOS of } T \text{ at } E = E_F)$

• best \vec{k} -point convergence for energy

• drawbacks (if used for metals):

- *w_{nj}*: not variational with the cange of ionic positions
- $\bullet \; \Rightarrow \;$ the new effective partial occupancies do not minimize the groundstate total energy
- \Rightarrow variation of occupancies $w_{n\vec{k}}$ w.r.t. the ionic positions would be necessary
- with US-PP and PAW practically impossible



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\vec{k} -point generation

choice of \vec{k} -points as implemented in VASP

- used files: KPOINTS, INCAR
- generate equally spaced \vec{k} mesh
- shift it by s_i (if shift is defined in KPOINTS)
- apply the symmetry operations of the symmetry group of the lattice if ISYM > 0: this includes the symmetries of the
 - Bravais lattice (POSCAR) ,
 - atomic positions (POSCAR) ,
 - pre-set MD-velocities (POSCAR) ,
 - magnetic ordering (INCAR)
- extract the \vec{k} points lying in the IBZ (\longrightarrow IBZKPT)
- calculate the proper weights $w_{\vec{k}_i}$



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Input files: KPOINTS

specifies the \vec{k} mesh to be used

Automatic mesh

- 0
- G (M)
- 444
- 0. 0. 0.

general format for scf runs, DOS

- header (comment)
- **2** $N_{\vec{k}} = 0$: automatic generation scheme
- **3** Γ (*M*)-centered MP grid
- # of subdivisions N_i along b_i
- **o** optional shift of the mesh (s_i)



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Input files: KPOINTS

high symm. lines 10 Line-mode rec 0 0 0 0.5 0.0 0 0.5 0.0 0 0.5 0.5 0.0 0.5 0.5 0.0 0.5 0.5 0.5

for bandstructure plots (DFT only)

eg for a simple cubic structure

- header (comment)
- intersections along each given symmetry line in the BZ
- ③ Γ−Χ
- 3 X-M
- **◎** *M*−*R*

this format must not be used for hybrid functional band structures



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Input files: INCAR

BZ-integration related Input Parameters

- ISMEAR=: BZ integration method : -1 (Fermi) | 0 (Gaussian) | 1,2 MP | -5 (Blöchl) for relaxation of metals use 1 or 2
- SIGMA: smearing width σ : S-contribution to F should not exceed a few meV/atom small-gap semiconductors!: $\sigma < \frac{1}{2}E_{gap}$
- **ISYM**: use of symmetrisation (\vec{k} -mesh spans the BZ or the IBZ)
 - -1 | 0 (no symm) | 1,2 (symmetry used)



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Setup of a proper \vec{k} -mesh

Some Hints

- always check for proper \vec{k} -mesh convergence before the production runs
- supercells: rescale the \vec{k} -mesh (preserve the density of the mesh)
- slabs (long axis \perp to the surface, eg z) : $N_1 imes N_2 imes 1$
- free atoms, molecules $1 \times 1 \times 1$ (Γ -point only)
- \vec{k} meshes for tetrahedra BZ-integration have to include Γ and the \vec{k} points at the BZ-edges
- the KPOINTS file format for DFT band-structure plots must not be used for calculations using hybrid functionals.